

# S580 GNSS Receiver GNSS Receiver for GIS & RTK Applications SSTONEX.



# S580 From GIS to Topography

S580 is a compact and lightweight GNSS receiver, with outstanding performance and centimeter accuracy. S580 tracks dual frequency signals and works with all satellite systems (GPS, GLONASS, BEIDOU, GALILEO and QZSS).

Compared to traditional GIS products, the \$580 is a high-precision, intelligent data acquisition receiver, that can be worn or attached to the pole, offering greater freedom of movement and flexibility. The \$580 can communicate with an external device such as a tablet, smartphone or PC via Bluetooth and Wi-Fi. Using the internal web interface, or through the Cube-connector APP, the receiver can be configured and prepared to receive RTK differential corrections and ready to be connected to any survey or GIS software.

The rubber protection cover, increase device protection, non-slip and no damage, the whole device protection class reaches IP67, and resists 1.2m drops on hard surfaces.





# ANDROID SYSTEM

Android system on board.



# **FULL CONSTELLATION SYSTEM**

GPS, GLONASS, BEIDOU, GALILEO, QZSS.



# **HIGH PRECISION**

High precision positioning, centimetric accuracy.



# **WEB UI**

Web interface for controlling and managing settings.



# **DATA TRANSMISSION**

Wi-fi, Bluetooth and external radio.



# RTK AND POST-PROCESSING

S580 can work in real time with RTK corrections and simultaneously record the raw data for post-processing.



# S580 GNSS Receiver

# Base/Rover RTK with Radio

The \$580 was designed as an RTK rover receiver to receive differential corrections from the Network. However, thanks to the external Stonex \$R02 radio, the receiver can also receive RTK corrections, from a base that transmits them via UHF radio modem, in the 410-470 MHz frequencies. The \$R02 external radio receives corrections from the base station and transmits them to the \$580 via Bluetooth.

This feature allows the \$580 receiver to receive (and transmit) RTK corrections and with this capability, the receiver can be used as base and/or as rover. This configuration is an excellent and complete low-cost solution.



# UNI EN ISO 9001:2015 - S580 - APRIL 2021 - VER03 - REV-02

# S580 TECHNICAL FEATURES

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RECEIVER	
	GPS: L1C/A, L2C
	GLONASS: L1OF, L2OF
Catallita sismala tuaslus d	BEIDOU: B1, B2
Satellite signals tracked	GALILEO: E1, E5b
	QZSS: L1C/A, L2C
	SBAS: L1
Channels	184
Position Rate	Up to 10 Hz
Signal Reacquisition	< 2 sec
RTK Initialization	Typically > 10 sec
Hot Start	Typically < 15 sec
Initialization Reliability	> 99.9 %

### POSITIONING<sup>1</sup>

STATIC POST PROCESSING		
Horizontal	< 2 cm + 1 ppm RMS	
Vertical	< 3 cm + 1 ppm RMS	
CODE DIFFERENTIAL PO	DSITIONING	
Horizontal	< 0.5 m RMS	
Vertical	< 1.0 m RMS	
REAL TIME KINEMATIC		
Fixed RTK Horizontal	< 2 cm + 1 ppm RMS	
Fixed RTK Vertical	< 3 cm + 1 ppm RMS	

# **INTEGRATED GNSS ANTENNA**

Full constellation GNSS antenna

# **HARDWARE**

Processor	SC20	
RAM	512 MB	
Flash Memory	8GB	
Operating System	Android	

# **EXTERNAL RADIO** (optional)

Model	SR02		
Type	Tx - Rx - Transceiver (2 watt)		
Frequency Range	410 - 470 MHz		
Channel Spacing	12.5 KHz / 25 KHz		
Marine ma Danca	3-4 Km in urban environment		
Maximum Range	Up to 10 Km with optimal conditions <sup>2</sup>		

# COMMUNICATION

I/O Connectors	TYPE-C connector support USB 2.0		
Bluetooth	2.1+EDR / 3.0 / 4.1 LE		
Wi-Fi	802.11 b/g/n		
Real time protocols	RTCM 3.x		

### **POWER SUPPLY**

Battery	Rechargeable 3.8 V - 6120 mAh	
Working Time	> 10 hours	
Charge Time	Typically 4 hours	

# PHYSICAL SPECIFICATION

Dimensions	136 mm x 78 mm x 31 mm
Weight	313g
Operating Temperature	-40°C to 65°C (-40°F to 149°F)
Storage Temperature	-40°C to 80°C (-40°F to 176°F)
Waterproof/Dustproof	IP67
Shock Resistance	Designed to endure a 1.2 m drop on concrete floor with no damage

# STANDARD ACCESSORIES

Power adapter, USB cable, Belt case, Pole mount

### **OPTIONAL ACCESSORIES**

Carbon fiber pole, Telescopic pole, Soft case



Illustrations, descriptions and technical specifications are not binding and may change



Accuracy and reliability are generally subject to satellite geometry (DOPs), multipath, atmospheric
conditions and obstructions. In static mode they are subject even to occupation times: the longer
is the Baseline, the longer must be the occupation time.

<sup>2.</sup> Varies with the operating environment and with electromagnetic pollution.